AMENDMENTS TO THE CLAIMS

This listing of claims will replace all prior versions and listing of claims in the application:

Listing Of Claims:

1. (Currently amended) A method of locating and displaying an image of a target, the method comprising the steps of:

sensing a triggering event generated by a human operator;

receiving <u>additional external</u> information that characterizes at least one machine-sensible feature of a target, said receiving step occurring substantially simultaneously with said sensing step; and

aiming a camera in response to said sensing and said receiving step, wherein said sensing step includes sensing a gesture indicting a direction of said target.

2. (Original) The method of claim 1, wherein said sensing step includes sensing a gesture of a human operator indicating a target.

3. (Canceled).

4. (Original) The method of claim 1, wherein said receiving step includes receiving speech from said human operator.

5. (Canceled).

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6. (Original) The method of claim 4, further including processing said speech for use with at least one machine sensor, said at least one machine sensor and said speech assisting in locating said target.

7. (Original) The method of claim 6, wherein said sensing step includes sensing a gesture indicting a direction from said human operator to said target.

8. (Currently Amended) The method of claim 6, wherein said processing step includes processing said voice information through a look-up table corresponding said speech to search criteria for use with said at ~~said~~ least one sensor.

9. (Original) The method of claim 8, wherein said look-up table is modifiable.

10. (Original) The method of claim 9, wherein said look-up table is modified by receiving information through the on-line global computer network.

11. (Original) The method of claim 9, wherein said look-up table is modified to include an additional voice input and a corresponding search criteria, said added voice input and said corresponding

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search criteria established by comparing previous association of

said added voice input with at least one machine sensible

characteristic of at least one correctly identified target

associated with said voice input, said machine sensible

characteristic being a basis for determining said corresponding

search criteria.

12. (Currently amended) A method of locating and displaying an

image of a target, the method comprising the steps of:

 scanning an area within the range of at least one sensor;

 identifying potential targets;

 storing information concerning machine sensible characteristics

and locations of said possible targets;

 sensing a triggering event, said triggering event generated by

a human operator;

 receiving <u>additional external</u> information that characterizes at

least one feature of said target, said receiving step occurring

substantially simultaneously with said sensing step; and

 aiming a camera in response to said sensing, storing and said

receiving steps, wherein said sensing step includes sensing a

gesture indicting a direction of said target.

13. (Previously presented)   A method of aiming a camera at a

target, comprising the steps of:

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inputting an indication of a position of a target;

inputting further information about a machine-sensible characteristic of said target;

aiming a camera at said target in response to said indication and said further information to reduce an error in said aiming, wherein said inputting an indication step includes inputting a gesture indicting a direction of said target.

14. (Previously presented)   A method of acquiring a target, comprising the steps of:

inputting spatial information to indicate a position of a target;

inputting further information about said target; and

orienting an instrument with respect to said target to acquire said target in response to said spatial information and said further information to reduce an ambiguity in said position, wherein said spatial information includes sensing a gesture indicting a direction of said target.

15. (Original)   A method as in claim 14, wherein said step of orienting includes orienting a camera.

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